User Study Script

**Setup**

* Setup dVRK – turn on, start teleop, start MATLAB, start user study control script
* Make sure ablation phantom is attached for the first half of the study

**Introduction + training**

* Welcome user – give them **consent form**
  + Session ID is tracked in recording, so assign one as you’d like
* User is invited to sit at the console, teach them how to telemanipulate using mode (1)

**Ablation Experiments**

* Start 1st ablation mode (1)
  + **Teach user how to keep a consistent force**
* Start 2nd ablation mode (2)
* Start 3rd ablation mode (3)
* Give user **feedback survey on ablation** and **pre-experiment survey**

**Palpation Experiments**

* Switch organs and reregister
  + Using file “”
  + NEED TO RELOAD MESH!
  + Update vision and robot registration to new organ (should happen automatically)
* Start 1st palpation mode (4)
* Start 2nd palpation mode (5)
* Give user **feedback survey on palpation**

**Finish**

* Check data saving?
* Give user **giftcard**
  + Social security?????